

# Principles of Computer Systems (MIT 6.826 Fall 2020)

## Course Notes

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## 1 Course Overview

- **Focus:** Correctness of complex computer systems through principled specifications and verification techniques.
- **Prerequisites:** Exposure to systems (e.g., 6.033, 6.006, 6.828).
- **Key Questions:** What makes a system correct? How do we prove correct execution under concurrency, faults, and optimizations?

## 2 Motivation and Complexity

- Concurrency: multiple threads/machines introduce nondeterminism.
- Distribution: network failures, partial machine crashes.
- Faults: power failures, disk/memory errors (fail-stop vs Byzantine).
- Performance and optimizations add subtle bugs.
- Evolution and maintenance amplify complexity.

## 3 Fault Tolerance and Crash Safety

### 3.1 Crash Safety Challenges

- Disk writes are atomic at sector granularity but not multi-block.
- System may crash at any point, leaving partial updates.
- Disk controllers may reorder buffered writes.

### 3.2 Write-Ahead Logging (WAL)

Ensures atomic multi-block updates via a log region:

1. **Log writes:** Write new block contents to log area.
2. **Commit record:** Update header indicating pending transaction.
3. **Apply updates:** Copy logged blocks to data region.
4. **Cleanup:** Clear header to complete transaction.

### 3.3 Recovery Procedure

- On reboot, read header. If transaction pending, replay log to data region.
- Replay is idempotent: reapplying writes is safe.

### 3.4 Barriers and Ordering

- Barrier between log and commit to ensure log durability before header update.
- Barrier between commit and apply to ensure header persisted before data writes.
- Barrier before cleanup to ensure data writes complete.

### 3.5 Optimizations and Subtleties

- **Log Bypass Writes:** Non-atomic data writes bypass log with careful barrier.
- **Checksum Logging:** Replace barrier by checksum of log region in header.
- Combination of optimizations can introduce subtle bugs (e.g., ext4 metadata leakage).

## 4 Principled Verification

### 4.1 Testing vs Model Checking vs Verification

- Testing finds bugs but cannot prove absence.
- Model checking explores state-space (limited by state explosion).
- Formal verification: code + specification + proof ensures correctness.

### 4.2 Verification Workflow

- **Code:** System implementation (e.g., file system, protocol).
- **Specification:** Formal definition of correctness properties.
- **Proof:** Manual or automated arguments that code meets spec.
- Tools: Coq, Lean, SMT solvers (Z3, CVC).

### 4.3 Success Stories

- AWS service design verification (Amazon engineers).
- CompCert: Verified C compiler.
- Verified cryptography in Chrome and Firefox (e.g., Ed25519, assembly generation).

## 5 Course Logistics

- Weekly lectures + paper discussions (paper summaries required).
- Lab assignments in Coq Proof Assistant (Fault-tolerant storage, replicated systems).
- Participation: Submit questions and answers on readings.
- Grading: Labs, paper summaries, participation.

## 6 Lecture: Amazon Paper Discuss & Intro to Specifications

### 6.1 Breakout Room Activity

Students were split into groups of 3–4 to discuss:

“The authors of the Amazon paper write formal specifications, yet do not use them to prove code correctness. What value do these specs bring to Amazon?”

After 5 minutes, groups shared key insights:

- **Design verification:** Specs expose design-level bugs early (e.g., logic loopholes or unintended behaviors), before any coding begins.
- **Evolution support:** With a spec in place, iterative changes can be validated against it, catching regressions without full reimplementations.
- **Documentation:** Formal specs serve as precise, unambiguous documentation—crucial in a large organization with many teams.
- **Forcing function:** Writing specs shifts focus from the “happy path” to all possible behaviors (safety/liveness), leading to more robust designs.

## 6.2 Prof. Lampson’s Perspective on Specifications

1. **Modularity:** Decouple client code from implementation details.
2. **Insight:** Highlight *what* the system must do, abstracting away *how*.
3. **Proof of correctness:** (Later labs/papers) Show that implementation traces are a subset of spec traces via simulation arguments.
4. **Model checking:** Automate bug finding by exploring reachable traces against the spec.

## 6.3 TLA<sup>+</sup> Basics

- **Actions** are predicates on current and next state, e.g.  $x' = x + 1$ .
- **Non-determinism:** Combine actions with  $\vee$ ; if multiple enabled, behavior is unpredictable.
- **Invariants:** Describe reachable states; crucial to reason about code only in valid states.

## 6.4 Spec Writing & Verification Workflow

1. Define *state variables* (keep this minimal to capture client-visible behavior).
2. Specify *operations* (transitions) in high-level notation (sets, comprehensions, nondeterministic choice).
3. (Optional) Perform *model checking* to catch bugs automatically.
4. For critical modules, derive *abstraction function* and perform simulation proofs:

$$c \xrightarrow{\text{code}} c' \implies f(c) \xrightarrow{\text{spec}} f(c')$$

## 6.5 Key Takeaways

- Specs are *not* just for proofs—they drive design, documentation, and testing.
- Amazon’s use of specs + model checking trades conclusive proofs for automation and speed.
- In this course, we’ll explore both model checking (Amazon style) and full formal proofs (Coq labs, research papers).

# 7 Lecture: Specifications & Abstractions

## 7.1 Homework Check-In

- **Software Foundations exercises:**
  - Homeworks (Coq tutorials) straightforward once syntax is learned.
  - Readings (Chapter proofs) more notation-heavy—expect greater clarity when you apply them in labs.

- *Tip*: Pattern-match existing proofs, and use Piazza/office hours for syntax-level questions.

## 7.2 Why Specs & Abstractions?

- **Goal**: Reason about all possible executions of some code.
- **Spec  $\rightarrow$  Proof  $\rightarrow$  Confidence**:

$$\{ \text{Pre}(s) \} f \{ \text{Post}(s', r) \}$$

where  $s, s'$  are program states,  $r$  the return value.

- **High-level vs. low-level views**:
  - *State-machine view* (Butler): global states  $\rightarrow$  transitions, traces, invariants.
  - *Hoare logic view* (today): function calls take  $s \rightarrow s'$ , specs as pre/post predicates.

## 7.3 Hoare Logic Primer

- $\{P\} f \{Q\}$ : if  $P(s)$  holds, then  $f$  terminates in  $s'$  with  $Q(s', r)$ .
- **Partial correctness**:  $\{P\} f \{Q\}$  says *if*  $f$  returns,  $Q$  holds; total correctness adds termination.
- **Sequencing rule**:

$$\frac{\{P\} x \{R\} \quad \{R\} y \{Q\}}{\{P\} x; y \{Q\}}$$

## 7.4 StaffDB Example

- **Code**:

```
def add(x):
    total := total + x
    count := count + 1

def average():
    require count > 0
    return total / count
```

- **Low-level specs (primitives)**:

$$\{ \top \} \text{read\_total} \{ s' = s \wedge r = s.\text{total} \}, \quad \{ \top \} \text{write\_total}(v) \{ s'.\text{total} = v, s'.\text{count} = s.\text{count} \}$$

- **Composing via sequencing**: decompose  $\text{add}(x)$  into  $\text{read\_total}$ ;  $\text{write\_total}(t + x)$ ;  $\dots$

## 7.5 Abstract-State Spec for StaffDB

- *Spec state*:  $h \in \text{list}(\mathbb{N}) = \text{history of inputs}$ .
- **High-level spec**:

$$\{ \top \} \text{add}(x) \{ h' = h[x] \}, \quad \{ |h| > 0 \} \text{average}() \{ r = \frac{\sum h}{|h|} \}$$

## 7.6 Abstraction Relation

$$R(s, h) \equiv s.total = \sum h \quad \wedge \quad s.count = |h|.$$

- $\{ \exists h. R(s, h) \} f \{ \exists h'. R(s', h') \wedge \Phi(h, h') \}$
- Layers proofs: once  $\{R\} f \{\Phi, R\}$  holds, we can treat  $f$  as a single abstract step on  $h$ .

## 8 Discussion: Everest Paper

### 8.1 Breakout Group Reports

- **Core challenges noted:** confusion over the one-page “cryptographic game” description, the interplay of  $F^*$ ’s memory model, and the status of Everest vs. Fully-Verified Everest.
- **Key insight:** They embed each real implementation call under an “ideal” oracle (the “magic log”) and prove the same high-level API spec holds whether you use the ideal model or the real cipher/MAC.

### 8.2 Magic-Log Model of Encryption

- *Ideal oracle:* upon `encrypt(key, p)`, return a fresh random  $c$ ; record  $\langle p, c \rangle$  in  $Log_{key}$ .
- *Decryption:* on `decrypt(key, c')`, look up  $\langle p, c' \rangle \in Log_{key}$ ; return  $p$  if found, else  $\perp$ .
- *Security rationale:* without the key  $\Rightarrow$  no access to  $Log$ , ciphertexts are uniform random.
- *Analogy:* one-time pad is a real-world instantiation: key = huge random pad, ciphertext =  $pad \oplus plaintext$ .

### 8.3 Nonce Usage

- **Nonce:** unique per-message, prevents replay—ensures identical plaintexts yield distinct ciphertexts.
- **Replay protection:** receiver tracks seen nonces; rejects duplicates.

### 8.4 Everest Project Overview

- **Goal:** drop-in replacement for OpenSSL/TLS stack with machine-checked correctness.
- **Stack layers:**
  1. *Crypto primitives* in  $F^*/Low^* \rightarrow C$  (AES, ChaCha, Poly1305, etc.).
  2. *Verified assembly* (via VEIL) for performance-critical loops.
  3. *Parser/Serializer* (EverParse) for ASN.1, X.509, DER.
  4. *TLS Handshake & Record Protocol* in  $F^*$ .
  5. *HTTPS Interface* compatible with OpenSSL API.
- **Deployment:** extract  $Low^* \rightarrow C$ ; compile with CompCert or GCC; “drop-in” for existing servers and clients.

### 8.5 Threat Model & Attacks

- **Heartbleed:** example of buffer-overflow in parsing; allowed arbitrary memory disclosure.
- **Man-in-the-Middle (MITM):** exploit certificate misuse or protocol bugs to intercept/decrypt.
- **Side-channels:** timing-dependent branches on secret key; mitigated by constant-time coding and memory-access patterns.

- **Certificate authentication:** X.509 chains, root CAs, NSS trust anchors; primary source of real-world misconfigurations.

## 8.6 Open Questions

- How well will Everest resist large-scale deployment attacks (phishing/MITM) versus opportunistic bugs?
- Can its F\* proofs scale to cover the full OpenSSL API surface without compatibility regressions?
- What performance-cost trade-offs remain after enforcing constant-time and fully verified parsers?

## 8.7 Limitations of Abstraction Functions

- *Insufficient state:* cannot record past executions (no “history”) or anticipate future choices (no “prophecy”).
- *Augmentations:*
  - **History variables** log every visited state/transition.
  - **Prophecy variables** predict which future transition will occur.
- *Completeness:* any implementation–spec trace inclusion can be witnessed by combining abstraction, history, and prophecy variables.

## 8.8 Trace Inclusion: Code vs. Spec

**Definition** A program **implements** its spec if every externally visible trace of the code is also allowed by the spec.

**Safety** “If the code returns a result, it satisfies the spec.”

**Liveness** “The code eventually returns a result (i.e. terminates).”

## 8.9 Sequential Example: Sorting

- **Spec:** relation on input/output arrays requiring the output to be a sorted permutation.
- **Code:** deterministic sort (e.g. `quicksort`) picks one allowed output.
- *External trace:* only initial and final arrays.
- *Internal steps:* pivot choices and swaps—hidden from the spec.

## 8.10 Simulation via Abstraction Functions

- An *abstraction function*  $f : \text{CodeState} \rightarrow \text{SpecState}$  must satisfy:
  1.  $\forall t_0$  initial:  $f(t_0)$  is initial in the spec.
  2. If  $t \xrightarrow{\pi} t'$ , then  $f(t) \xrightarrow{\pi} f(t')$ .
- By induction,  $\text{Traces}(\text{code}) \subseteq \text{Traces}(\text{spec})$ .
- A *state invariant* restricts attention to reachable states.

## 8.11 Example: Write-Back Cache

- **Spec:** memory  $m : \text{Addr} \rightarrow \text{Val}$ , operations `READ`/`WRITE`.
- **Code:** adds a cache  $c : \text{Addr} \rightarrow \text{Val}$  plus main memory  $m$ .

- *Abstraction*: overlay  $\text{mem}(a) = c(a)$  if defined, else  $m(a)$ .
- *Invariant*:  $|\text{dom}(c)| = C_{\text{size}}$  is preserved by LOAD/FLUSH.

## 8.12 Extra Spec State & History Variables

- **Spec**: DB stores a list of inputs to compute mean/variance.
- **Code**: maintains only  $(n, \text{sum}, \text{sum2})$ .
- *Solution*: add a history variable  $h$  (the full list) to code; relate  $(n, \text{sum}, \text{sum2})$  to  $\text{fold}(h)$  via an invariant.

## 8.13 Abstraction Relations

- Generalize  $f$  to a relation  $R \subseteq \text{Code} \times \text{Spec}$ .
- If  $(t, s) \in R$  and  $t \xrightarrow{\pi} t'$ , then  $\exists s'$  with  $s \xrightarrow{\pi} s'$  and  $(t', s') \in R$ .
- Supports many-to-one and one-to-many state mappings.

## 8.14 Internal Transitions

- Code or spec may take unobservable steps (*internal*).
- *Simulation*: a code step labeled  $\pi$  must match a sequence of spec steps whose visible projection is  $\pi$ .

## 8.15 Prophecy Variables

- Required when the spec makes a *premature choice*—e.g. dropping messages at crash time or agreement at `allow`.
- A prophecy variable  $p$  is chosen up front to predict which future branch will fire.
- Formal rules ensure prophecy does not disable real code steps and preserves the external trace.

## 8.16 Limitations of CompCert's Correctness Specification

- **Liveness**
  - Distinguishes *terminate* vs. *diverge*, but cannot decide termination (undecidable).
  - No guarantees that a non-faulting program will *eventually* produce output.
- **Performance**
  - No complexity or latency bounds: an efficient C algorithm may compile to a much slower binary.
  - CompCert itself may take unbounded time or memory on pathological inputs.
- **Memory Safety & Undefined Behavior**
  - Behaviors after UB (e.g. buffer overflows, integer overflow, null-pointer dereference) are unconstrained.
  - Only *safe* (UB-free) C programs are in scope; no protection if the source invokes UB.
- **Security Properties**
  - No guarantees on confidentiality or integrity (e.g. side-channel resistance, secret erasure).
  - Optimizations may expose secrets or enable timing attacks.
- **Application-Level Correctness**

- Preserves C semantics, but does not verify that the *application logic* is correct or meets its spec.

## 8.17 Static Analysis: A Lightweight Alternative

- **What is static analysis?**

- A “lightweight cousin” of full formal verification: no global proofs, but automatic, scalable checks.
- Universally adopted in industry to catch bugs early, without running the program.
- Active research—new tools and techniques emerge constantly.

- **Case studies: Google FindBugs vs. Facebook Infer**

- Both tools check for *partial* specifications (common bug patterns, API-misuse, null dereferences), not full program correctness.
- Co-designed with real dev workflows—tool authors work closely with engineers to choose which properties to check.

- **Spec vs. developer goals**

- *Full verification* demands a complete spec proof; static analysis targets *universal invariants* (no null-pointer use, no unchecked user input, etc.).
- Emphasis on *actionable* warnings:
  - \* Low “effective” false-positive rate (Google): a warning is *not* false if a dev fixes it.
  - \* Low missed-bug rate (Facebook): focus on catching real in-the-wild defects (crashes, security, data races).
- Feedback loop trust: compile-time review-time batch dashboards. Early, in-context alerts build trust and drive fixes.

- **Scalability via locality & compositionality**

- Most checks are *intra-procedural*: look at a few lines or one function—fast, low overhead.
- *Inter-procedural* bugs (null returned deep in call chains, unsanitized user input) require summaries:
  - \* **Infer** automatically infers per-function “mini-specs” to scale whole-program data-flow race detection.
- Incremental, parallel analyses: each function can be analyzed independently, then re-composed.

- **Key takeaways**

- Static analysis succeeds when it solves concrete developer pain points—fast feedback, low noise, clear fixes.
- Tools must be integrated into IDEs or code-review (compile-time ideal) to minimize context-switch cost.
- Co-design with engineers, monitor actionable fix rates, and tune analyses (precision vs. recall) to real workloads.

## 8.18 SybilFS: Specifying and Testing POSIX File Systems

- **Motivation:**

- Real-world file systems (ext3, HFS+, etc.) follow informal POSIX “man-page” specs.
- Goal: a *precise*, executable spec to drive exhaustive tests and uncover subtle bugs.



- Impact: influenced POSIX editors to tighten ambiguities.
- **Key challenge—non-determinism:**
  - POSIX leaves many behaviors *unspecified* (e.g. error-code ordering, bytes-returned by `read()`, directory-entry order).
  - Concurrency in `readdir()`—interleaved creates/deletes yield many possible valid traces.
  - Must capture “all implementations” under one spec.
- **SybilFS approach:**
  - *Lem DSL* for spec:
    - \* Define abstract OS state (process table, open-file map, directory contents).
    - \* Label transitions: `call(pid, op, args), return(pid, result)`, plus for reordering concurrency.
    - \* Non-deterministic choice: Lem’s “`|||`” to enumerate all allowed outcomes.
  - *Workload generator*:
    - \* Automatically explore syscall sequences to drive corner-case behaviors.
    - \* No oracle needed—SybilFS “oracle” is spec membership check.
  - *Online checking*:
    - \* Track *set* of possible spec states matching the observed trace so far.
    - \* After each system call / return label, prune spec states whose transition label `observed label`.
    - \* Empty match set `implementation–spec divergence` (bug!).
- **Directory iteration model:**
  - Maintain per-`opendir()` “*must*” and “*may*” sets for entries present throughout vs. those concurrently created/deleted.
  - Guarantees:
    - \* “Must” entries always returned.
    - \* “May” entries may or may not appear, in any order, possibly interleaved.
- **Results and takeaways:**
  - SybilFS found both spec ambiguities and real file-system bugs in Linux, BSD, macOS.
  - Precise, executable specs power stronger black-box testing than ad hoc workloads.
  - Non-determinism modeling + aggressive pruning keeps state-space manageable.

## 8.19 Separation Logic: Foundations and Modular Reasoning

- **Why Separation Logic?**
  - Tackles pointer-aliasing by *separating conjunction* ( $P * Q$ ): asserts  $P, Q$  hold on disjoint heap fragments.
  - Enables concise *local* specs and proofs for heap-manipulating programs.
  - Scales to concurrency (ownership transfer) and to large codebases (Facebook Infer).
- **Core Assertions:**
  - $x \quad v$ : “cell  $x$  contains  $v$ .”
  - $P * Q$ :  $P$  holds on one part of the heap,  $Q$  on a disjoint part.
  - `emp`: the heap is empty.
  - *Entailment*  $P \vdash Q$ : whenever  $P$  holds, so does  $Q$ .

- **Inductive Predicates:**

- `list(x)` or `tree(x)`: describe linked structures by recursion.
- Example:

$$\text{list}(x) \begin{cases} x = \text{null}: \text{emp}, \\ x \neq \text{null}: \exists d, z. x \mapsto (d, z) * \text{list}(z). \end{cases}$$

- Extensions can track *contents*: `list_addr(x, L)` pairs shape with stored data  $L$ .

- **Specifying Procedures:**

- *Hoare triple*:  $\{P\} C \{Q\}$  means “if  $P$  holds, then after  $C$ ,  $Q$  holds.”
- Example `prepend(x, a)`:

$$\{ \text{list}(x) \} \text{new}(r, a, x) \{ \text{list}(r) * \text{list}(x) \}.$$

- Garbage-collecting a tree:

$$\{ \text{tree}(t) \} \text{delete\_tree}(t) \{ \text{emp} \}.$$

- **Local Reasoning—Frame Rule:**

$$\frac{\{P\} C \{Q\}}{\{P * R\} C \{Q * R\}} \quad (\text{if } C \text{ does not touch } R).$$

- Modify only the footprint of  $P$ , leave  $R$  intact.
- Yields highly *modular* proofs—reason about one heap fragment at a time.

- **Mechanization with Iris:**

- Uses *weakest precondition*  $\text{WP } e\{Q\}$  instead of triples.
- Spatial context lists separating-heap hypotheses; proof tactics mutate them in-place.
- Recursive calls handled by assuming WP spec holds on subcalls.

## 8.20 Verified File System (FSCQ)

- **Why Verify a File System?**

- *Critical infrastructure*: all real systems persist data onto a filesystem.
- *Stable spec, buggy implementations*: POSIX-style behavior rarely changes, yet crashes and subtle bugs still occur.
- *Crash safety*: power loss or kernel panic may strike at any point—must prove no on-disk corruption.
- *Asynchronous disk I/O*: controller buffers writes unpredictably; crash may lose or reorder pending writes.

- **FSCQ Artifact**

- **Gallina** implementation of a simple FS + logging layer.
- Coq proofs over a *CrashCore* logic: functional correctness *and* crash-recovery guarantees.
- Extraction to Haskell, compiled as a **FUSE** filesystem—live mountable on Linux.

- **Abstract Disk Model**

- Addresses  $\mapsto$  *lists* of values: pending writes collect in order.
- `read(a)` returns the *last* entry in list; does not drop older entries.
- `write(a, v)` appends  $v$  to the list at  $a$ .

- **sync** “flushes”: collapse each list to its last element only.
- **crash + recover**: for each  $a$ , nondeterministically pick one entry from its list and discard the rest.

- **Logging Layer as Two Synchronous Disks**

- *Active disk*: collect **log\_write** into a transient, synchronous “logical” disk.
- *Committed disk*: last-committed state, also synchronous.
- **commit**: atomically copy entire Active→Committed.
- **recover** after crash: reset Active←Committed.
- Yields *all-or-nothing* semantics: pending writes never leak unless **commit** finishes.

- **Crash-Core Logic Extension**

- Each operation spec carries (1) a *post-condition* for normal return, and (2) a *crash-condition* for mid-execution failure.
- **write(a,v)** crash-condition: either before or after write—but never “partial” sector update.
- Global proof of **recover()**:
  - \* Show every step’s crash-condition implies the **recover** pre-condition.
  - \* *Idempotence*: **recover**’s crash-condition equals its pre-condition, so repeated crashes during recovery remain safe.

## 8.21 Concurrency and x86 TSO

- **Motivation**: real-world CPUs expose *weak* memory behaviors—hardware optimizations (caches, store-buffers, OOO, speculation) break the intuitive SC view.
- **Sequential Consistency (SC)**
  - All loads and stores appear as *atomic* steps on a single, shared memory.
  - Programmers can interleave per-thread steps but never observe “out-of-thin-air” reorderings (e.g.  $\langle 0, 0 \rangle$  in the classic two-store/two-load example is impossible).
  - Clean abstraction, but too expensive for high performance.
- **Weak Memory Toys**:
  - *Store-buffering*: stores go into a per-core buffer before hitting memory.
  - *Loads* may read from the buffer or from main memory atomically.
  - *Background/driven flushes* and explicit **MFENCE** let buffered writes propagate.
  - *Speculation & out-of-order execution* further reorder effects unless fenced.
- **TSO Abstract Machine**:
  - One “hardware thread” per SMT lane; each has its own store buffer.
  - **Load(a)** atomically returns the newest pending or committed value.
  - **Store(a,v)** enqueues  $(a \mapsto v)$  in the local buffer only.
  - **Fence/MFENCE** forces buffer → memory flush before continuing.
  - **LOCK**-prefixed instructions perform their R/W plus buffer flush atomically.
- **Litmus-Test Examples**:
  - Two-store/two-load “MP” test admits  $(0, 0)$  under TSO (stores sit in buffers).
  - “Independent-Reads-Of-Independent-Writes” (IRIW) only fails if two readers share a buffer—TSO forbids it with per-thread buffers.
- **OS vs. Hardware Threads**:

- OS context switch must *flush* a process’s buffer (or treat it as empty) when descheduling, to preserve TSO at the user level.
- Kernel/user boundary (IRET) on x86 implicitly acts as a fence.
- **Axiomatic Specs (Intel/AMD):**
  - Informal English “rules” + forbidden litmus tests—hard to cover all cases, and sometimes inconsistent with actual chips.
  - Contrast: TSO paper provides a crisp, formal *abstract machine* ideal for both reasoning and teaching.
- **Key Takeaway:** *TSO’s simple cartoon (per-thread store buffers + fences) captures exactly what x86 offers—enabling correct low-level concurrency without drowning in cache/coherence/speculation details.*

## 8.22 Finding Concurrency Bugs (TSVD)

- **Why concurrency bugs are hard:**
  - *Coverage explosion:*  $\#threads \times \#interleavings$  grows combinatorially.
  - *Poor reproducibility:* a rare schedule may trigger a crash once but then never recur.
- **Testing vs. static analysis:**
  - *Static analyzers* (lock-set, thread-sanitizer) must infer cross-call contexts; often too imprecise or expensive.
  - *Dynamic testing* runs real interleavings—but must both define a “bug” and drive schedules to expose it.
- **Bug definition in TSV-D:**
  - Each TSV (thread-safety-violation) is a *conflicting* read/write or write/write on an API-specified data structure.
  - API authors annotate each TType with a “read set” (methods that only observe) and “write set” (methods that mutate).
  - Violation  $\equiv$  two methods from these sets run *concurrently*.
- **No false positives (by design):**
  - “Bug”  $\equiv$  observed violation of their TSV contract (e.g. concurrent `Map.Add()` vs. `Map.TryGet()`).
  - Benign data races (e.g. counters) are excluded because only library-declared APIs are monitored.
- **Schedule-driving via delays (“traps”)**
  - *Trap points:* on each API call, record (object, op).
  - Inject `Sleep()` before a trapped operation to amplify “near-miss” races.
  - If another thread’s conflicting API runs during the sleep, report a TSV.
- **Heuristics to avoid wasted delays:**
  - *Near-miss detection:* only trap when two ops on the same object occurred within  $T_{ms}$  in recent execution.
  - *Delay-inference:* if delaying one op also delays its partner by  $\approx T$ , infer they’re synchronized (e.g. via a lock) and stop trapping there.
- **Strengths & limits:**
  - Very low user effort: drop-in .NET tool finds real bugs in standard collections.

- Low “false alarm” rate on API-annotated data structures—over half of reported violations were fixed by developers.
- Misses bugs in un-annotated or custom APIs; may over-delay in hot paths.

## 8.23 Lab 3 Recitation: Crash-Safe Log

- **Motivation:**

1. *Atomicity via write-ahead log*: append all entries, then “commit” by updating a header.
2. *Crash safety*: on crash, recovery must see either the old log or the fully appended new log—no torn writes.
3. *API-design practice*: define `get`, `append`, `reset` purely by postconditions, then implement from first principles.

- **Logging API spec (in `log_api.file`):**

- `state`: `list<block>` (unbounded).
- `get()`: returns entire log (no state change).
- `append(xs)`:
  - \* May succeed (return `true` and extend log) or fail (return `false`, no change).
  - \* *Crash-safety*: if crash occurs during append, final log is either old or `old++xs`.
- `reset()`: clears log (atomic or no-op on crash).

- **Underlying disk API:**

- Fixed-size array of blocks, atomic single-block read/write.
- We build multi-block `append` plus crash-safe commit.

- **Crash-safe design (header + payload):**

- On disk, block 0 stores `n = current log length`.
- Blocks `1..n` hold valid log entries; blocks `> n` are garbage.
- `get()`: read header `n`, then read blocks `1..n`.
- `append(xs)`:
  1. Write entries of `xs` into blocks `n + 1 ... n + |xs|`.
  2. Finally write updated length `n + |xs|` into header.
- Crashing before header write leaves header at old `n` (old log); crashing after gives new log.
- `reset()`: single atomic write of 0 to header.

- **Pseudocode sketch:** [basicstyle=] `get(): n ← disk.read(0) return foldr (i from 1 to n) (++) [disk.read(i)] []`

`append(xs): n ← disk.read(0) if n + |xs| + 1 > DISK_SIZE then return false for i, x in enumerate(xs) : disk.write(n + 1 + i, x) disk.write(0, n + |xs|) return true`

`reset(): disk.write(0, 0)`

- **Verification strategy:**

- *Abstraction relation* between disk array and logical log:

$$(\exists n). 0 \leq n \leq \text{DISK\_SIZE} - 1 \wedge (\forall i < n. \text{disk}[i + 1] = \text{log}[i]).$$

- Prove `get`, `append`, `reset` satisfy their specs under crash semantics.
- Use loop-combinator lemmas (`for_range`, `for_each`) with tailored loop invariants.
- Automate common disk-update rewrites with `auto_rewrite_with_upd`; discharge arithmetic side-conditions via `lia`.

## 8.24 Proving Concurrency Correct

- **Today's Goals:**

1. Understand how to prove a concurrent implementation refines its specification.
2. See what is *easy* vs. *hard* in concurrency proofs.
3. Learn how to build “large” atomic actions from smaller ones.

- **Two Views of “Spec vs. Code”:**

**State-Machine View:** – Global states  $s$ , atomic “steps”  $A(s, s')$ ; define a *trace* or *behavior* as a sequence of states.

- A *spec* = set of allowed traces;  $\text{code} \subseteq \text{spec} \iff \text{code's visible traces are in spec.}$
- Proof by *invariants*: find  $I(s)$  such that

$$I(s_0) \wedge A(s, s') \implies I(s'),$$

then  $I$  holds forever.

**Language/Command View:** – Primitives: pure expressions,  $x := e$ . Composition via  $;$ ,  $\text{if}$ ,  $\text{while}$ ,  $\parallel$ , etc.

- Semantics via *weakest preconditions* (or Hoare triples):  $wp(c, Q)$ .
- Proofs by *wp-calculus* or triples rather than global invariants.

- **Threads in State Machines:**

- Each thread  $t$  has its own program counter  $pc_t$  in a large state.
- “Next” relation is  $\bigvee_t A_t(s, s')$ , where  $A_t$  fires only if  $pc_t$  matches.
- Invariant must hold after *every* thread's step.

- **Refinement/Data Abstraction:**

- A mapping  $m : S_{\text{code}} \rightarrow S_{\text{spec}}$ . Lift to traces pointwise.
- Code implements spec *under*  $m$  if  $\forall \tau_c. \text{trace}_c(\tau_c) \implies \text{trace}_s(m(\tau_c))$ .
- Proved by showing  $\text{init}_c \implies m^{-1}(\text{init}_s)$  and  $\text{next}_c \implies m^{-1}(\text{next}_s)$ .

- **Atomic Actions:**

- *Hardware-provided*: e.g. load/store of one word, test&set.
- *By composition*: group  $a; b$  into one atomic action if  $b$  “commutes” with every action in other threads:

$$a; b \subseteq b; a \quad (\text{as sets of traces}).$$

- **Commutativity Cases:**

1. *Disjoint variables*: actions touch different vars.
2. *Producer-Consumer*: only communication via **put/get** on a buffer.
3. *Locking*:  $a$  holds lock  $\ell$ ,  $b$  also requires  $\ell$ —so  $b$  cannot interleave.
4. *Abstraction*: replace a complex sequence by an atomic “black-box” once proven correct.

- **Mutex Acquire/Release:**

- **acquire( $m$ )**: atomically wait for  $m = \text{free}$ , then set  $m = \text{self}$ .
- **release( $m$ )**: if  $m = \text{self}$ , set  $m = \text{free}$  (else **havoc**).
- *Two-phase locking*: hold *all* needed locks before touching shared data, then release at end.

- **Simulation Proof Sketch** of atomicity for  $a; b$ :

- Show  $\{ab\} \subseteq \{ba\}$  by case analysis on whether the interfering action  $c$  interleaves before or after.
- Use a relational invariant linking “ $a$  done” vs. “not yet done” in the other schedule.

- **PlusCal Example:**

- A simple `spinlock` using atomic `TestAndSet`:

```
while TestAndSet(m) = 1 do skip od;
```

but *bad* on single-CPU: no one else can release.

- A *realistic* multi-processor lock (Lamport’s bakery / spinlock variants):
  - \* Processes numbered  $1 \dots N$ , each with label-guarded steps.
  - \* Carefully placed assertions (**Assert**) to encode invariants at key labels.
  - \* Proof obligation: for each thread PC  $\ell$ , every other thread’s step preserves all asserts.

- **Key Takeaways:**

- Always try to fit your concurrency protocol into *disjoint*, *producer-consumer*, or *locking* patterns.
- If you stray into “hard” concurrency (no commuting discipline), you must do a full correctness proof or risk elusive bugs.
- PlusCal/TLA+ give a *state-machine* style with invariants; the *language* (wp) style scales to code-level but needs external mapping to hardware.

## 8.25 Reading *Armada*: Mechanized Concurrency Proofs

- **Admin: Lab4 Options**

- Default: prove *replicated disk* with crash safety in our current framework.
- Alternatives (notify instructors early): explore Daphne, Iris, VST, or free-form project.

- **Why *Armada*?**

- Machine-checked proofs of *fine-grained* concurrent code, *without locks*.
- Realistic x86-TSO memory model, not just sequentially consistent.
- Illustrates *state-machine* reasoning at scale and automation techniques.

- **Proof Foundations:**

**Invariants** –global state predicates preserved by every step.

**Abstraction Relations** –relate concrete state-machine transitions to high-level spec.

**Mover/Reduction** –classify each code step as *right-/left-/both-/non-mover*.

- Right-movers can be delayed past others; left-movers can be advanced earlier.
- Sequence of  $(rights)n(lefts)$  compresses into one atomic action.

- **Armada Pipeline:**

1. Write both *spec* and *code* in the same Armada language (plus nondet. `*`, `choose`).
2. *Translator* generates an explicit state machine: states = full memory+PCs; steps = individual atomic transitions.
3. Developer annotates *reduction strategy* (regions of right/left movers, fences, TSO-elimination).
4. *Proof generator* emits Daphne proof scripts showing:

$$Traces_{code} \subseteq Traces_{spec}.$$

5. Daphne (with Z3 backend) discharges thousands of small commuting and invariant-preservation lemmas.

- **Key Mechanization Trick: “Sigma”**

- Each transition is a *deterministic* function  $next(s, \sigma) \rightarrow s'$  by packaging all nondet. choices (malloc result, thread-ID, branch \*) into a **step** record  $\sigma$ .
- Commutativity proof becomes a simple *equality* check:

$$next(next(s, \sigma_i), \sigma_j) = next(next(s, \sigma_j), \sigma_i).$$

- **Automation vs. Manual Proof:**

- State-machine approach: many small, uniform obligations  $\rightarrow$  amenable to SMT automation.
- Language-based (Iris, separation logic): fewer but more *creative* invariants, harder to auto-solve.

- **Next Lecture:** Compare with *Iris*’s *language-level* concurrency logic and verify how its proof style and tooling differ from the state-machine + mover approach.

## 8.26 Reading the Iris Blog Post

- **Motivation:**

- *Iris* embeds concurrency reasoning as a *program logic*, not a state machine.
- Blog post walks through a toy “bank” example to expose *lock invariants*, *ghost state*, and **iProp** proof mode.
- Goals today:
  1. Explain *lock invariants* via Go/Rust idioms and *Iris*’s formalization.
  2. Introduce *ghost variables* (fractional permissions, update, splitting).
  3. Read and interpret a typical *Iris* proof obligation (**WP**— *Iris*’s weakest-precondition goal).

- **From Functional to Concurrent Imperative:**

- Original spec: **transfer**(bank, b, n) = **new\_bank** in pure functional style.
- Single-threaded imperative: pointers & separation logic to prove that **transfer** preserves total sum.
- Naïve concurrent spec fails (interleaved transfers break “start = b” assumption).
- We want each account’s transfer to be atomic *and* composable with other independent transfers.

- **Lock Invariants:**

- *Go*: convention “// m protects b1, b2”—only a comment, unenforced.
- *Rust*: **Mutex**<Balances> ties data to the lock type; scope-based unlock.
- *Iris*: associate each lock with an *invariant*  $P$  s.t.

$$\{ \text{lock}(l) \} \text{ acquire } l \{ P \} \quad \text{and} \quad \{ P \} \text{ release } l \{ \text{lock}(l) \}$$

- Inside  $P$  one may bundle both *points-to* assertions and *pure facts* (e.g. balances sum to 0).

- **Ghost Variables & Fractional Permissions:**



- *Ghost var*  $\mapsto^q v$  holds that “ghost  $\gamma$  has value  $v$  with fraction  $q \in (0, 1]$ .”
- Rules:
  1. *Allocation*: introduce fresh  $\gamma \mapsto^1 v$ .
  2. *Split / Combine*:  $\gamma \mapsto^1 v \Leftrightarrow \gamma \mapsto^q v * \gamma \mapsto^{1-q} v$ .
  3. *Persistence*: two fragments  $\gamma \mapsto^{q_1} v * \gamma \mapsto^{q_2} v \implies v$  equal.
  4. *Update*: owning  $\gamma \mapsto^1 v$  lets you change to any  $v'$ .

- **Bank Example in Iris:**

- Two accounts **b1**, **b2** each protected by its own lock invariant:

$$\exists b, v. (\mathbf{b1} \mapsto b * \gamma_1 \mapsto^{\frac{1}{2}} v * \Box(b = v)) \quad * \quad (\text{same for } b2, \gamma_2)$$

- *Global invariant*:  $\gamma_1 \mapsto^{\frac{1}{2}} v_1 * \gamma_2 \mapsto^{\frac{1}{2}} v_2 * (v_1 + v_2 = 0)$ .
- **transfer(n)** proof outline:
  1. **acquire b1**; **acquire b2**—get both lock invariants.
  2. Update physical pointers: **\*b1 -= n**; **\*b2 += n**.
  3. **open** both invariants to gain full ghost ownership, update  $\gamma_1, \gamma_2$ , then **close**.
  4. **release b2**; **release b1**—re-establish each  $P$ , including  $b = v$  and sum 0.
- **check\_consistency()** acquires both locks, **open** global invariant, checks  $v_1 + v_2 = 0$ , then **close&release**.

- **Reading Iris WP Goals:**

*Persistent context* facts duplicable across threads (**is\_lock**, *invariants*).

*Spatial context* exclusive resources (*points-to*, *ghost perms*).

**WP triple** mixes Iris proof-mode steps (**iIntros**, **iDestruct**, **iCombine**, ...) with standard separation logic.

- **Beyond the Example:**

- *Custom ghost state*: monotonic counters, authoritative sums, spatial region algebras.
- *Atomicity specs*: you can prove **transfer** itself is logically atomic (*vs.* merely safe).
- *RustBelt*: semantic type-soundness of **Vec<T>**—unsafe implementation, safe API guaranteed by Iris.

- **Next Time:** We’ll continue exploring Iris by mechanizing a small concurrent stack and seeing how *higher-order* invariants and *fancy updates* extend these techniques.

## 8.27 IronFleet: Verified Distributed Systems

- **Why Distributed Systems?**

- Concurrency across machines
- High communication costs (e.g. cache misses or network latency)
- Partial failures—must remain available despite node crashes

- **Five-Layer Verification Architecture**

1. *Abstract Spec* (à la Lamport): global “God’s-eye” view with a visibility relation.
2. *Protocol Level*: hosts execute **ph\_next** actions atomically; communicate by message sends/receives; prove a global invariant in TLA/PlusCal style.
3. *Host Code*: each host action is pure sequential code; prove it refines the protocol’s atomic action via reduction (movers).

4. *Network Model*: UDP-style packets; maintain a ghost-journal of sends/receives to reason about message flow.
5. *Composition*: combine host+network to get the full distributed system; then compose refinements up to the abstract spec.

- **Key Proof Technique: Reduction & Movers**

- *Process actions*: commute with everything (both movers).
- *Receive actions*: right-movers (can be delayed).
- *Send actions*: left-movers (can be advanced).
- Any host-action matching  $R \rightarrow T \rightarrow L$  pattern is atomic by commuting out other hosts' steps.

- **Example1: Distributed Lock**

- Spec: sequence of holders; each **Acquire** appends the holder's ID.
- Impl: hosts send “grant” and “ack” packets with a counter; invariant tracks last **Acquire** packet to reconstruct holder sequence.

- **Example2: Replicated State Machine (Paxos RSM)**

- Spec: behave like a single deterministic machine on a command stream.
- Protocol: classic Paxos rounds—propose, accept/quorum, learn; must preserve *quorum-intersection* to ensure agreement.
- Optimizations: batching, leader election (view changes), state transfer (snapshot), reply caching.
- Liveness under timed fairness assumptions (beyond pure asynchrony).

- **Example3: Rebalancing Key–Value Store**

- Data partitioned by key range; may “move” a range by sending in-flight split packets.
- Invariant: every key is either owned by exactly one host or in a pending transfer packet.
- Reliable transmission and ordering layered over UDP.

- **Pragmatic Considerations**

- Trust assumptions: spec, compiler/runtime, OS, hardware.
- Verified libraries for containers, marshalling, data-structure invariants.
- Ghost state for unbounded history (network journal).
- Automation trade-offs: powerful SMT vs. careful annotations; modular proofs over large codebases.
- 4× code overhead; needs expert proof engineers; constraints on code shape for automation.

## 8.28 Ivy/I4: Automated Protocol Invariant Discovery

- **Context: Protocol Verification**

- A sub-problem of distributed-system verification, distinct from implementation correctness.
- Separates “does the protocol work?” from “can I write correct code to implement it?”
- Fits into IronFleet’s five-layer stack at the *protocol-level* (between host code and global spec).

- **Why Protocols Are Hard**

1. *Unreliable Networks*: messages may be lost, delayed, duplicated, reordered.

2. *Node Failures*: crashes vs. network partitions are indistinguishable; recovering state is tricky.
3. *Dynamic Membership / Byzantine Faults*: (beyond I4's scope) arbitrary misbehavior complicates consensus.

- **Ivy: SMT-Backed Protocol Checker**

- User writes **state** relations (e.g. `semaphore(s)`, `link(c,s)`).
- Defines **init** predicate and **action** transitions.
- Safety spec = predicate on reachable states (e.g. no two clients hold same lock).
- Ivy encodes: `[label=()]`
- $Init \Rightarrow Invariant$ ,
- $Action \text{ preserves } Invariant$  as Z3 queries  $\Rightarrow$  fully automated safety proof.

- **Inductiveness vs. Safety**

- *Safety bubble*: all states satisfying spec predicate.
- *Reachable bubble*: all states reachable by stepping from **init**.
- Spec predicate *may not* be inductive (closed under transitions).
- Need a *stronger* inductive invariant (blue bubble) satisfying: `[label=()]`
- $init \subseteq I$ ,
- $\forall s \in I, s \rightarrow s' \implies s' \in I$ ,
- $I \subseteq spec$ .

- **I4: Automatic Invariant Inference**

- Leverages a bounded-model checker (AVR) to exhaustively explore a *small* instance (e.g. 1server, 2clients).
- AVR synthesizes a compact formula characterizing *all* reachable states in that instance.
- I4 lifts/generalizes this formula to *unbounded* parameters to propose a global inductive invariant.
- Feed back into Ivy; if too weak, increase small-model bounds and repeat.

- **Demo: Lock Service**

- Simple client–server lock protocol in Ivy.
- Initial spec fails inductiveness test (must forbid “server still holds lock” when client thinks it does).
- Strengthen invariant (add `link(c,s)  $\implies$   $\neg$  semaphore(s)`).
- Ivy checks *init* and every *action* automatically in seconds.
- Add “client-to-client transfer” action; Ivy again verifies safety with no manual proof.

- **Trade-Offs & Applicability**

- Extremely easy to verify safety of unbounded protocols (no Coq/Tac scripting).
- Relies on: decidable fragment of logic, small-model generalization.
- *Deadlock* is a liveness—not safety—concern (Ivy supports some liveness via cycle-finding).
- Open question: can small-model invariant inference extend to richer concurrency proofs (e.g. Iris/Armada)?

## 8.29 Verifying Software-Defined Networks

- **Motivation**

- *Critical infrastructure*: Every distributed system relies on IP/Ethernet forwarding.
- *Narrow, well-scoped spec*: Packet-in/packet-out behavior vs. arbitrary stateful services.

- *High complexity*: Distributed control (switches, failures, reconfiguration) hides bugs.
- **Traditional Networks**
  - Each switch independently stores (*config, routing state*).
  - Switches run distributed protocols (e.g. OSPF, BGP) to build forwarding tables.
  - *Challenges*: Inconsistent configs, complex failure recovery, per-switch debugging.
- **Software-Defined Networks (SDN)**
  - *Centralized controller*: Single global “brain” programs all switches.
  - *Data-plane switches*: Fast path uses locally cached *flow tables*.
  - *Benefits*: Simplified policy, hot-swap hardware, unified vendor API.
  - *Risks*: Controller single point of failure; reconfiguration must preserve connectivity.
- **NetCore/Featherweight OpenFlow**
  - *NetCore DSL*:
    - \* `match cond` on packet headers
    - \* `modify` primitive header fields (TTL, IP)
    - \* `action` selects output ports
    - \* `union/restrict` to combine rules
  - *Flow table IR*: Ordered list of `{match,modify,action}` entries, resolved by priority.
  - *Featherweight OpenFlow*: Controller–switch protocol
    - \* `PacketIn` → controller if no match
    - \* `Add/DeleteFlow` from controller to switch
    - \* `Barrier` to enforce order
- **Correctness via Certified Compilation**
  - *Compile-time*:  $\text{NetCore} \xrightarrow{\text{certified compiler}} \text{controller binary} + \text{runtime}$
  - *Theorem*:  $\text{Controller} + \text{runtime} \simeq \text{NetCore spec}$
  - *Trace inclusion*:
    - \*  $\text{Implementation traces} \subseteq \text{Spec traces}$  (safety)
    - \*  $\text{Spec traces} \subseteq \text{Implementation traces}$  (bisimulation  $\approx$  liveness)
- **Limitations & Outlook**
  - *Static configurations*: Paper models one fixed NetCore program—no dynamic updates.
  - *Controller reliability*: Single-host performance and fault-tolerance not addressed.
  - *Higher-level policies*: End-to-end liveness (e.g. “all flows are logged”) must be layered atop NetCore.

## 8.30 Empirical Study of “Verified” Distributed Systems

- **Paper goal:**
  - *Ask*: Do complex, machine-checked DS actually eliminate bugs?
  - *Approach*: Audit three systems (IronFleet, Verdi, Chapar) for real faults.
- **Why bugs persist:**
  - *Spec gaps*: What the proof assumes vs. real API behavior.
  - *Shim errors*: Unverified “glue” layers (OS, network, I/O) violate axioms.
  - *Tooling faults*: Build scripts or provers skip or ignore proof failures.
- **Finding bugs:**

- *Fuzzing shims*: Inject resource errors, partial I/O, packet loss/duplication.
- *Cross-checking*: Compare against alternate implementations or hand-written tests.
- *Manual audit*: Inspect build logs, proofs, spec comments for mismatches.
- **Representative faults**
  - IronFleet** – *Tooling*: Build script ignores Z3 exit signals; proof errors go unnoticed.
    - *Spec*: “Exactly-once” duplicate filtering not guaranteed by spec.
  - Verdi** – *Shim*: TCP receive may yield partial or no messages; file partial writes crash on replay.
    - *Tooling*: Deep recursion in extracted OCaml overflowed stack (no liveness guarantee).
  - Chapar** – *Shim*: UDP axioms omitted packet loss/duplication; custom marshal API left stale bytes.
    - *Spec*: Causal-consistency invariants broken by unchecked network behavior.
- **Lessons & best practices**
  - *Lean, precise spec*: Drive proofs by writing and verifying small example apps atop your spec.
  - *Integral proof workflows*: Always require explicit “success” outputs, not just absence of errors.
  - *Harden shims*: Fuzz and test every OS / network primitive; prefer narrow, verified APIs.
  - *Layered verification*: Push boundaries sensibly—too large → complexity, too small → unsound assumptions.
  - *Operational checks*: Combine formal guarantees with staged rollouts, runtime monitoring, and alarmed fallbacks.

### 8.31 Komodo: Minimal-Hardware Enclaves via Verified Monitor

- **Motivation:**
  - Intel SGX provides secure enclaves in hardware—but is complex, hard to extend.
  - *Goal*: Recreate enclave isolation & attestation with minimal hardware, pushing policy into software.
- **Security background:**
  - *Isolation* trades off with *sharing*—must authenticate who may access which resource.
  - *AuthN/AuthZ* via **guard** mediating requests against system policy.
  - *Attestation*: map concrete channels (e.g. crypto pipes) to high-level principals via “speaks-for” chains.
  - *Threats*: hostile OS, side-channels, induced faults, denial of service.
- **Enclave architecture:**
  - *Host* (OS/VMM) is untrusted; software monitor and enclave code must enforce security.
  - *Monitor*: tiny “baby hypervisor” mediates transitions (SMC, exceptions, interrupts) between:
    - \* Normal world (untrusted OS)
    - \* Enclave world (trusted code)
  - *Hardware support* (if only against software threats):
    - \* Protected RAM region (OS can’t touch).
    - \* Secure control-transfer instructions in CPU.

\* Root key for attestation; RNG for crypto.

- **Attestation protocol:**

1. `attest(key)`: monitor returns  $\text{MAC}_{HK}(ms, key)$ , binding enclave measurement  $ms$  to signing key.
2. `verify(key, ms, tag)`: check MAC under hardware root key  $HK$  “key speaks for  $ms$ ”.
3. Chain trust: hardware key monitor enclave.

- **Formal verification:**

- *Spec*: 12 Monitor calls plus enter/exit semantics; enforces:
  - \* *Confidentiality*: public outputs depend only on public inputs.
  - \* *Integrity*: trusted outputs depend only on trusted inputs.
- *Model*: ARM machine model in “Veil” pseudo-assembly; opaque oracles resolve non-determinism.
- *Proof*:
  - \* Verify each Monitor transition implements spec (Dafny+Z3).
  - \* Non-interference (relational refinement) over world-switch boundaries.

- **Key takeaways:**

- Small, verified monitor proves enclave isolation, attestation—avoids SGX microcode complexity.
- Even tiny code bases harbor corner-case bugs—verification catches subtle “page A=pageB” errors.
- Strong spec + minimal TCB + verified toolchain yields high assurance with modest hardware.

## 8.32 Non-Interference and Confidentiality in CertiKOS

- **Integrity vs. Confidentiality**

- *Integrity* (functional correctness) ensures “no corruption” of state.
- *Confidentiality* means “no unauthorized disclosure” of secrets.
- Confidentiality is much harder: must prevent any leakage, not just wrong answers.

- **Example: Two-Block Disk**

- Block0 holds userA’s data, Block1 holds B’s.
- Naïve rule “B never reads 0” still allows many leaks (out-of-bounds reads, metadata APIs, remappers).
- Any non-determinism in spec or implementation can be exploited to distinguish A’s secret.

- **Non-Interference as Two-Safety**

- *One-trace safety*: “no single bad trace.”
- *Two-trace safety* (non-interference): for any two initial states indistinguishable to B, all B’s observations along both executions must remain identical.
- B’s entire visible behavior—reads, outputs, syscalls—must be independent of A’s secret.

- **Observation Functions**

- $\text{Obs}_{\text{spec}}(p, s)$ : what principal  $p$  is allowed to see in abstract state  $s$ .
- $\text{Obs}_{\text{code}}(p, c)$ : what  $p$  actually observes at the implementation level.
- Must satisfy  $\text{Obs}_{\text{code}}(p, c) \subseteq \text{Obs}_{\text{spec}}(p, s)$  whenever  $c$  implements  $s$ .

- **Proof Outline**

1. *Spec-level determinism*: every abstract step from  $s \rightarrow s'$  preserves  $Obs_{\text{spec}}$ .
2. *Lowering*: if two spec states are indistinguishable, their code states remain indistinguishable under  $Obs_{\text{code}}$ .
3. By induction on steps, B's final observations cannot distinguish A's secret.

- **Challenges and Corner Cases**

- *Specification leaks*: forgetting to include page-table layout or PID allocation in  $Obs_{\text{spec}}$  can break proof.
- *Implementation leaks*: exposing extra channels (e.g. “used-blocks” API) not modeled in  $Obs_{\text{code}}$ .
- *Concurrency nondeterminism*: context switches break the two-trace alignment  $\rightarrow$  solved by “local semantics,” collapsing other threads into a single yield step.

- **Takeaways**

- True confidentiality requires reasoning about *pairs of executions* (two-safety).
- Complete determinism (in spec & code) simplifies proofs but is often impractical.
- Designing precise observation functions is crucial: they define both allowed spec observables and actual code leakage.
- Practical non-interference for OS kernels (like CertiKOS) must handle VM mappings, syscalls (fork/PID), and concurrency carefully.

### 8.33 What Formal Proofs Give—and Don't—for Security

- **Paper context**

- Authors: Toby Murray (SCL4 microkernel), security and verification experts.
- Genre: philosophical “meta-paper” on the gap between *proved* theorems and *real-world* security.
- Goal: set realistic expectations for using proofs in security projects.

- **Why proofs seem ideal for security**

- Security is a *negative goal*: “no attacker can ever break in,” so every corner case matters.
- Formal proofs force you to *consider all cases* and eliminate human oversight.
- A concise, correct *specification*—if achievable—yields machine-checked confidence.

- **Why proofs alone may fall short**

1. *Mis-modeled reality*: CPU models often omit nondeterminism, timing, undocumented registers, or rarified instructions.
2. *Incomplete threat model*: hardware bugs (e.g. Rowhammer), side-channels, SMM/JTAG debug paths, physical tampering.
3. *Uncaptured APIs*: e.g. PID allocators, “used-blocks” queries, speculative features.
4. *Specification vs. implementation drift*: theorem may not say what you think, or be hard to interpret (weeks to grok seL4's statement!).

- **Code changes and “Venn diagram” of edits**

- $P$ : changes needed to make the proof go through.
- $A$ : changes needed for real-world security.
- $P \cap A$ : *ideal*—you only change what both demand.
- $P \setminus A$ : proof-overhead edits (e.g. off-by-one tweaks, proof-friendly refactorings).

- $A \setminus P$ : attacks your proof missed (e.g. Rowhammer bitflips, timing leaks).
- $\exists V \subseteq (P \setminus A)$ : *worse edits* that actually weaken security.

- **Value of proofs, despite limits**

1. *Qualified guarantees*: “system is secure *if* these precise (and extractable) assumptions hold.”
2. *Structured exploration*: writing down state, spec, abstraction & proof uncovers bugs & clarifies design.

- **Defense in depth**

- Even with a *proved* memory-safe engine, you still layer ASLR, canaries, sandboxing, etc.
- Backup measures mitigate the inevitable *threat-model drift* encountered in practice.

### 8.34 Automated, “Push-Button” Verification with Rosette & Servo

- **Motivation:** Eliminate

- Low-level memory/overflow bugs (buffer overrun, div0, UB).
- Logical errors (missing sanity checks, path-specific flaws).
- *Design* bugs (API flaws that break isolation or leak secrets).

- **Illustrative UB in C:**

- Multiply two 16bit `uint16_t` via `c = (uint32_t)(a*b)`
- `-00` yields correct  $a * b$ , `-02` triggers signed-overflow UB and returns “wrong” value.
- GCC exploits “signed-overflow is UB” to optimize away.

⇒ even a one-line “innocent” routine can go wrong under real compilers.

- **“Push-Button” Verification Stack:**

**Rosette** → **Servo** → *your verifier* → SMT solver

- *Rosette*:
  - \* Embeds your interpreter or DSL in a symbolic language.
  - \* Lifts *concrete* interpreter into *symbolic* evaluator.
  - \* Provides *knobs* (symbolic reflection, custom providers) to tune encodings.
- *Servo*:
  - \* Framework atop Rosette for low-level code (RISC-V, LLVM IR, BPF).
  - \* Builds “no-proof” verifiers: spec + implementation  $\xrightarrow{\text{Servo}}$  SMT.
- *Jitterbug*:
  - \* A Servo-based JIT-compiler verifier for LinuxBPF:
    - Found and fixed real bugs in the upstream kernel.
    - Shipped in Linux since March 2024.

- **Symbolic vs. Bounded Encoding:**

- *Pure symbolic execution*: forks at every branch, merges later → *path-explosion*.
- *Bounded model-checking*: one-step “merge” after each instruction → huge symbolic terms.
- *Rosette’s hybrid*: uses *type-guided merges* to keep encoding size polynomial & precise.

- **Profiling & Tuning “Magic Box”:**

- *Symbolic profiler* spots expensive eval sites (e.g. symbolic PC in an interpreter).



- *Custom provider* (e.g. `split-pc`): force concrete cases on PC, collapse paths early.
- Iteratively “repair” your spec/interpreter until verification finishes.
- **Retrofitting Classic Verifiers:**
  - Ported seL4-style security monitors (CERTiKOS, Nova, etc.) to RISC-V + Servo.
  - Proved each system-call lemma (e.g. `yield`, `alloc`, `exit`) separately so that SMT can handle it.
  - Turned days of manual Coq proofs into ~weeks of Servo setup per API.
- **Practical Impact:**
  - Verified new BPF “JIT” compiler and plugged it into Linux kernel.
  - Uncovered real bugs in both Linux core and ARM support libraries.
  - Demonstrated “push-button” verification can enter production—low manual-proof overhead.

### 8.35 Why Not Proofs? Engineering for Reliability

- **The “Software Crisis” (1960s–’90s):** Formal methods promised to tame exploding complexity, but industrial uptake was limited.
- **High-Reliability Case Studies:**
  - *Therac-25 (1985)*: Sloppy UI+ concurrency bugs in radiation machine software → patient overdoses.
  - *Ariane5 (1996)*: Unhandled FP-to-integer overflow in Ada spec caused dual guidance-computer failure → self-destruct.
  - *Telephone Exchanges (1970s–’90s)*: Carrier-grade “six-9s” availability achieved with rigorous engineering, not proofs.
- **Economics of Reliability:**
  - Only mission-critical (avionics, banking, cloud infra) can justify the cost of exhaustive proofs.
  - Most software (desktop apps, web services) tolerates occasional bugs—“approximate” vs. “precise” software.
- **Tony Hoare’s Recipe for Quality (1996):**
  1. *Rigorous Design & Review*: Inspect and cure specification flaws before coding.
  2. *Testing as QA*: Use tests to *drive* specs, detect faults, and feed back into design—*not* to “test in” quality.
  3. *Continuous Debugging*: Fix problems immediately in development and production (DevOps loop).
  4. *Over-Engineering & Fault Isolation*: Fail fast, restart components, isolate modules; accept redundancy.
  5. *Informal Math*: Leverage discrete-math ideas (invariants, pre/postconditions) in everyday specs.
- **When to Turn to Formal Methods:**
  - Concurrency and failures—rare, adversarial interleavings that evade testing.
  - Use lightweight *modeling* (TLA+/PlusCal+model-checking) to *design-verify* distributed protocols (e.g. Amazon S3).
  - Full machine-checked proofs reserved for small kernels or crypto stacks with huge consequences.

- **Other Key Lessons:**

- *DevOps & Agile*: Developers operate their own code, enabling rapid feedback and regression control.
- *Component Reuse & Moore's Law*: Off-the-shelf databases, languages, and GPUs tolerated by vast compute headroom.
- *Technical Debt Awareness*: Regularly repay code “debt” before it blocks future feature delivery.
- *Procurement and Partnership*: Cooperative customer–vendor relationships crucial—antagonism leads to failure.